# Squeezing of quantum states 

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## Squeezing of quantum states

- Introduction
- Motivation: why squeezing?
- Basics of squeezing
- Hamilton canonical equations and squeezing rate
- Examples
- Conclusion



## Why squeezing?

■ Metrology: suppressed noise of interferometers

- optics:detection of gravitational waves
- squeezed atomic spin states: magnetometry
- atomic clocks

■ Quantum information processing: irreducble resource

- quantum teleportation of continuous variables
- quantum cryptography
- quantum computation with continuous variables


## Why squeezing?

Measurement noise 100 times lower than the quantum-projection limit using entangled atoms

[Hosten et al. (Kasevich group)]

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Gravitational wave detection, LIGO

[www.ligo.caltech.edu; PRL 116, 061102 (2016)]

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Gravitational wave detection: GEO600 (LIGO collaboration),
R. Schnabel

[Abadie et al., Nature Physics, 7, 962-965 (2011)]

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## Why squeezing?

## Quantum information processing with squeezed states

■ Quantum teleportation of continuous variables [Vaidman, PRA 49, 1473 (1994)].
■ Quantum cryptography with continuous variables (e.g., [Hillery, PRA 61, 022309 (2000)]

- Quantum computation with continuous variables (e.g., [Lloyd \& Braunstein, PRL 82, 1784 (1999)])
- Analogue computation,
- quantum simulators,
- to have universal computer, necessary to have Hamiltonian of higher than quadratic nonlinearity in $x$ and $p$.



## Basics of squeezing

## Squeezing

Example: harmonic oscillator
■ Hamiltonian:

$$
H=\frac{\hat{p}^{2}}{2 m}+\frac{1}{2} m \omega^{2} \hat{x}^{2}
$$

- Coherent states: saturate uncertainty relation

$$
\begin{aligned}
\Delta x & =\sqrt{\frac{\hbar}{2 m \omega}} \\
\Delta p & =\sqrt{\frac{\hbar m \omega}{2}} \\
\Delta x \Delta p & =\frac{\hbar}{2}
\end{aligned}
$$

## Basics of squeezing

## Squeezing

Example: harmonic oscillator
Coherent states: saturate uncertainty relation


## Basics of squeezing

## Squeezing

Example: harmonic oscillator
Creation and annihilation operators:

$$
\begin{aligned}
\hat{x} & =\sqrt{\frac{\hbar}{2 m \omega}}\left(\hat{a}+\hat{a}^{\dagger}\right) \\
\hat{p} & =-i \sqrt{\frac{\hbar m \omega}{2}}\left(\hat{a}-\hat{a}^{\dagger}\right) \\
{[\hat{x}, \hat{p}] } & =i \hbar \\
{\left[\hat{a}, \hat{a}^{\dagger}\right] } & =1 \\
H & =\hbar\left(\hat{a}^{\dagger} \hat{a}+\frac{1}{2}\right)
\end{aligned}
$$

## Basics of squeezing

## Squeezing

Example: harmonic oscillator Squeezed coherent states: can also saturate uncertainty relation, but, e.g.:

$$
\begin{aligned}
\Delta x & <\sqrt{\frac{\hbar}{2 m \omega}} \\
\Delta p & >\sqrt{\frac{\hbar m \omega}{2}} \\
\Delta x \Delta p & =\frac{\hbar}{2}
\end{aligned}
$$

p


## Basics of squeezing: detection

## Homodyne detection



$$
\begin{aligned}
& \hat{a}_{1}=\frac{1}{\sqrt{2}}(\hat{a}+\hat{b}), \quad \hat{a}_{2}=\frac{1}{\sqrt{2}}(\hat{a}-\hat{b}) \\
& I_{1} \propto \hat{a}_{1}^{\dagger} \hat{a}_{1}=\frac{1}{2} \hat{a}^{\dagger} \hat{a}+\frac{|b|}{2}\left(\hat{a}^{\dagger} e^{i \varphi}+\hat{a} e^{-i \varphi}\right)+\frac{|b|^{2}}{2} \\
& I_{2} \propto \hat{a}_{1}^{\dagger} \hat{a}_{1}=\frac{1}{2} \hat{a}^{\dagger} \hat{a}-\frac{|b|}{2}\left(\hat{a}^{\dagger} e^{i \varphi}+\hat{a} e^{-i \varphi}\right)+\frac{|b|^{2}}{2}
\end{aligned}
$$

## Basics of squeezing: detection

## Homodyne detection



$$
I_{1}-I_{2} \propto|b|\left(\hat{a}^{\dagger} e^{i \varphi}+\hat{a} e^{-i \varphi}\right)
$$

Example: $\varphi=0$

$$
I_{1}-I_{2} \propto|b|\left(\hat{a}^{\dagger}+\hat{a}\right) \propto \hat{x}
$$

Example: $\varphi=\pi / 2$

$$
I_{1}-I_{2} \propto i|b|\left(\hat{a}^{\dagger}-\hat{a}\right) \propto \hat{p}
$$

## Basics of squeezing: detection

Homodyne detection


Noise squeezing [G. Breitenbach dissertation, 1998; Nature 387, 471 (1997)]

## Basics of squeezing: squeezing production

## Parametric down-conversion



## Basics of squeezing: squeezing production

## Parametric down-conversion

$$
H=\chi\left(\hat{b} \hat{a}_{1}^{\dagger} \hat{a}_{2}^{\dagger}+\hat{b}^{\dagger} \hat{a}_{1} \hat{a}_{2}\right)
$$

Parametric down-conversion, degenerate case

$$
H=\chi\left(\hat{b} \hat{a}^{\dagger 2}+\hat{b}^{\dagger} \hat{a}^{2}\right)
$$



Basics of squeezing: squeezing production

## Kerr nonlinearity

(index of refraction proportional to light intensity)

$$
H=\chi \hat{n}^{2}
$$

Strong pulses propagating in optical fibres


## Basics of squeezing: squeezing production

## Jaynes-Cummings model

a two level atom and a single-mode field

$$
\hat{H}_{J C}=g\left(\hat{a} \hat{\sigma}_{+}+\hat{a}^{\dagger} \hat{\sigma}_{-}\right)
$$


[C. W. Woods and J. Gea-Banacloche, J. Mod. Opt. 40, 2361-2379 (1993)]

Classical Hamiltonian $H(x, p)$, equations of motion

$$
\begin{aligned}
\dot{x} & =\frac{\partial H}{\partial p} \\
\dot{p} & =-\frac{\partial H}{\partial x}
\end{aligned}
$$

Continuity equation

$$
\begin{aligned}
\frac{\partial \varrho}{\partial t} & =-\sum_{k} \frac{\partial j_{k}}{\partial q_{k}} \\
j_{k} & =\varrho \dot{q}_{k}
\end{aligned}
$$

Liouville theorem

$$
\frac{d \varrho}{d t}=0
$$

## Hamilton canonical equations and squeezing rate

## Phase space is the countryside, Hamiltonian is the elevation



## Rules of motion:

- Follow the countour line (constant elevation), hill on your left, valley on your right,

■ speed is proportional to the slope magnitude.

## Hamilton canonical equations and squeezing rate

Phase space is the countryside, Hamiltonian is the elevation


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Derivation of the squeezing rate
Variation matrix

$$
V=\left(\begin{array}{cc}
\left\langle\Delta x^{2}\right\rangle & \langle\Delta x \Delta p\rangle \\
\langle\Delta x \Delta p\rangle & \left\langle\Delta p^{2}\right\rangle
\end{array}\right) \equiv\left(\begin{array}{cc}
V_{x x} & V_{x p} \\
V_{x p} & V_{p p}
\end{array}\right),
$$

for a state centered in $\left(x_{0}, p_{0}\right)$.

Derivation of the squeezing rate
Change of position

$$
\begin{aligned}
\tilde{x}_{0}+\Delta \tilde{x} \approx & x_{0}+\Delta x+\frac{d}{d t}\left(x_{0}+\Delta x\right) d t \\
= & x_{0}+\Delta x+\frac{\partial H\left(x_{0}+\Delta x, p_{0}+\Delta p\right)}{\partial p} d t \\
\approx & x_{0}+\Delta x+\frac{\partial H\left(x_{0}, p_{0}\right)}{\partial p} d t \\
& +\left(\frac{\partial^{2} H\left(x_{0}, p_{0}\right)}{\partial p^{2}} \Delta p+\frac{\partial^{2} H\left(x_{0}, p_{0}\right)}{\partial x \partial p} \Delta x\right) d t
\end{aligned}
$$

## Derivation of the squeezing rate

Change of momentum

$$
\begin{aligned}
\tilde{p}_{0}+\Delta \tilde{p} \approx & p_{0}+\Delta p+\frac{d}{d t}\left(p_{0}+\Delta p\right) d t \\
= & p_{0}+\Delta p-\frac{\partial H\left(x_{0}+\Delta x, p_{0}+\Delta p\right)}{\partial x} d t \\
\approx & p_{0}+\Delta p-\frac{\partial H\left(x_{0}, p_{0}\right)}{\partial x} d t \\
& -\left(\frac{\partial^{2} H\left(x_{0}, p_{0}\right)}{\partial x^{2}} \Delta x+\frac{\partial^{2} H\left(x_{0}, p_{0}\right)}{\partial x \partial p} \Delta p\right) d t
\end{aligned}
$$

## Derivation of the squeezing rate

New central position and momentum:

$$
\begin{aligned}
& \tilde{x}_{0} \approx x_{0}+H_{p} d t, \\
& \tilde{p}_{0} \approx p_{0}-H_{x} d t,
\end{aligned}
$$

new deviations:

$$
\begin{aligned}
& \Delta \tilde{x} \approx \Delta x+\left(H_{x p} \Delta x+H_{p p} \Delta p\right) d t \\
& \Delta \tilde{p} \approx \Delta p-\left(H_{x p} \Delta p+H_{x x} \Delta x\right) d t
\end{aligned}
$$

## Derivation of the squeezing rate

Assuming $\langle\Delta x\rangle=\langle\Delta p\rangle=0$, the new variances are (up to the first order in $d t$ )

$$
\begin{aligned}
\left\langle\Delta \tilde{x}^{2}\right\rangle & \approx\left\langle\Delta x^{2}\right\rangle+2\left(H_{x p}\left\langle\Delta x^{2}\right\rangle+H_{p p}\langle\Delta x \Delta p\rangle\right) d t \\
\left\langle\Delta \tilde{p}^{2}\right\rangle & \approx\left\langle\Delta p^{2}\right\rangle-2\left(H_{x p}\left\langle\Delta p^{2}\right\rangle+H_{x x}\langle\Delta x \Delta p\rangle\right) d t \\
\langle\Delta \tilde{x} \Delta \tilde{p}\rangle & \approx\langle\Delta x \Delta p\rangle+\left(H_{p p}\left\langle\Delta p^{2}\right\rangle-H_{x x}\left\langle\Delta x^{2}\right\rangle\right) d t
\end{aligned}
$$

## Derivation of the squeezing rate

In terms of the variation matrix:

$$
\tilde{V}=S V S^{T},
$$

where

$$
S=\left(\begin{array}{cc}
1+H_{x p} d t & H_{p p} d t  \tag{1}\\
-H_{x x} d t & 1-H_{x p} d t
\end{array}\right) .
$$

## Derivation of the squeezing rate

For initially isotropic and uncorrelated fluctuations, i.e., $\left\langle\Delta x^{2}\right\rangle=\left\langle\Delta p^{2}\right\rangle=\sigma^{2}$, and $\langle\Delta x \Delta p\rangle=0$ :

$$
\begin{aligned}
\left\langle\Delta \tilde{x}^{2}\right\rangle & \approx \sigma^{2}\left(1+2 H_{x p}\right) d t \\
\left\langle\Delta \tilde{p}^{2}\right\rangle & \approx \sigma^{2}\left(1-2 H_{x p}\right) d t \\
\langle\Delta \tilde{x} \Delta \tilde{p}\rangle & \approx \sigma^{2}\left(H_{p p}-H_{x x}\right) d t
\end{aligned}
$$

Eigenvalues of the new variance matrix $\tilde{V}$ :

$$
\tilde{V}_{ \pm}=\frac{\left\langle\Delta \tilde{x}^{2}\right\rangle+\left\langle\Delta \tilde{p}^{2}\right\rangle}{2} \pm \frac{1}{2} \sqrt{\left(\left\langle\Delta \tilde{x}^{2}\right\rangle-\left\langle\Delta \tilde{p}^{2}\right\rangle\right)^{2}+4\langle\Delta \tilde{x} \Delta \tilde{p}\rangle^{2}}
$$

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## Derivation of the squeezing rate

Inserting the transformed variance:

$$
\tilde{V}_{ \pm}=\sigma^{2}(1 \pm Q d t)
$$

where

$$
\begin{equation*}
Q=\sqrt{\left(H_{p p}-H_{x x}\right)^{2}+4 H_{x p}^{2}} \tag{2}
\end{equation*}
$$

is the squeezing rate.
[T.O., PRA 92, 033801 (2015)]

Orientation and rotation of the squeezing ellipse

Transformation matrix $S$, general starting variance matrix:

$$
S=\left(\begin{array}{cc}
\cos (\phi-\epsilon) & -\sin (\phi-\epsilon) \\
\sin (\phi-\epsilon) & \cos (\phi-\epsilon)
\end{array}\right)\left(\begin{array}{cc}
1+\frac{Q d t}{2} & 0 \\
0 & 1-\frac{Q d t}{2}
\end{array}\right)
$$

$$
\times\left(\begin{array}{cc}
\cos \phi & \sin \phi \\
\sin \phi & \cos \phi
\end{array}\right)
$$



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Orientation and rotation of the squeezing ellipse

Up to the first order in $\epsilon$ and $d t$, one finds

$$
S=\left(\begin{array}{cc}
1+\frac{Q d t}{2} \cos 2 \phi & \epsilon+\frac{Q d t}{2} \sin 2 \phi  \tag{3}\\
-\epsilon+\frac{Q d t}{2} \sin 2 \phi & 1-\frac{Q d t}{2} \cos 2 \phi
\end{array}\right) .
$$

Comparing this with Eq. (1) one finds

$$
\begin{aligned}
Q \cos 2 \phi & =2 H_{x p}, \\
Q \sin 2 \phi & =H_{p p}-H_{x x}, \\
2 \epsilon & =\left(H_{x x}+H_{p p}\right) d t,
\end{aligned}
$$

with $Q$ given by Eq. (2).

## Orientation and rotation of the squeezing ellipse

Rotation angle

$$
\tan 2 \phi=\frac{H_{p p}-H_{x x}}{2 H_{x p}}
$$

and assuming that $\epsilon$ evolves with time as $\epsilon=\omega_{\nu} d t$, one gets

$$
\begin{equation*}
\omega_{v}=\frac{H_{x x}+H_{p p}}{2} \tag{4}
\end{equation*}
$$

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Compensation of motion of the uncertainty ellipse

Rotation center at $\left(x_{R}, p_{R}\right)=(x, p)+\left(R_{x}, R_{p}\right)$ with

$$
R_{x}=-\frac{H_{x}}{\omega_{c}}, \quad R_{p}=-\frac{H_{p}}{\omega_{c}}
$$

angular frequency of the motion of the center

$$
\begin{equation*}
\omega_{c}=\frac{H_{x}^{2} H_{p p}+H_{p}^{2} H_{x x}-2 H_{x} H_{p} H_{x p}}{H_{x}^{2}+H_{p}^{2}} \tag{5}
\end{equation*}
$$



Compensation of motion of the uncertainty ellipse

To compensate the drift, add the Hamiltonian

$$
H_{\mathrm{ad} 1}=-\frac{1}{2} \omega_{c}\left[\left(x-x_{R}\right)^{2}+\left(p-p_{R}\right)^{2}\right] .
$$

To keep the optimal orientation, add

$$
H_{\mathrm{ad} 2}=-\frac{1}{2}\left(\omega_{v}-\omega_{c}\right)\left[\left(x-x_{0}\right)^{2}+\left(p-p_{0}\right)^{2}\right]
$$

Combined Hamiltonian $H_{a d}=H_{a d 1}+H_{a d 2}$,

$$
\begin{equation*}
H_{\mathrm{ad}}=-\frac{1}{2} \omega_{v}\left[\left(x-x_{r}\right)^{2}+\left(p-p_{r}\right)^{2}\right]+\text { const. } \tag{6}
\end{equation*}
$$

with the center localized at

$$
\left(x_{r}, p_{r}\right)=\left(x_{R}, p_{R}\right)+\left(1-\frac{\omega_{c}}{\omega_{v}}\right)\left(x_{0}-x_{R}, p_{0}-p_{R}\right)
$$

## Examples

## Harmonic oscillator

$$
H=\frac{1}{2} \omega\left(p^{2}+x^{2}\right)
$$

Eq. (2) yields $Q=0$.
Rotation frequencies $\omega_{v}=\omega_{c}=\omega$.


## Examples

## Free particle

$$
H=\frac{1}{2 m} p^{2} .
$$

Squeezing rate $Q=1 / m$, optimum orientation of the uncertainty ellipse $\theta=\pi / 4$, rotations $\omega_{v}=1 /(2 m)$, and $\omega_{c}=0$.


## Examples

## Free particle

In terms of quantum optical bosonic operators:

$$
\begin{aligned}
& \hat{x}=\frac{1}{\sqrt{2}}\left(\hat{a}^{\dagger}+\hat{a}\right), \\
& \hat{p}=\frac{i}{\sqrt{2}}\left(\hat{a}^{\dagger}-\hat{a}\right),
\end{aligned}
$$

the Hamiltonian is

$$
H=\frac{1}{2} \hat{p}^{2}=-\frac{1}{4}\left(\hat{a}^{\dagger 2}+\hat{a}^{2}\right)+\frac{1}{2}\left(\hat{a}^{\dagger} \hat{a}+\frac{1}{2}\right),
$$

i.e., parametric down-conversion plus harmonic oscillator.

## Examples

## Inverted oscillator

$$
\frac{1}{2} \zeta\left(p^{2}-x^{2}\right)
$$

Squeezing rate $Q=2 \zeta$, optimum orientation $\theta=\pi / 4$, no rotation, $\omega_{v}=0$.


## Examples

## xp-Hamiltonian

$$
H=\zeta x p
$$

Classical counterpart of the quantum operator

$$
\hat{H}=\frac{1}{2} \zeta(\hat{x} \hat{p}+\hat{p} \hat{x})=\frac{i}{2} \zeta\left(\hat{a}^{\dagger 2}-\hat{a}^{2}\right),
$$

i.e., parametric down-conversion.

Squeezing rate $Q=2 \zeta$, optimum orientation $\theta=0$, no rotation, $\omega_{v}=0$.


## Examples

## Pendulum

$$
H=\frac{1}{2} p^{2}-\cos x
$$

Squeezing rate

$$
Q=1-\cos x=2 \sin ^{2} \frac{x}{2},
$$

rotation $\omega_{v}=\cos ^{2} \frac{x}{2}$

## Examples

## Kerr nonlinearity

$$
H=\chi\left(p^{2}+x^{2}\right)^{2},
$$

Squeezing rate

$$
Q=8 \chi\left(p^{2}+x^{2}\right)
$$

rotation

$$
\begin{aligned}
\omega_{v} & =8 \chi\left(p^{2}+x^{2}\right) \\
\omega_{c} & =4 \chi\left(p^{2}+x^{2}\right) \\
\left(x_{r}, p_{r}\right) & =\frac{1}{2}\left(x_{0}, p_{0}\right)
\end{aligned}
$$

## Examples

## Kerr nonlinearity

Compensating Hamiltonian

$$
H_{\mathrm{ad}}=-4 \chi\left(x_{0}^{2}+p_{0}^{2}\right)\left[\left(x-\frac{x_{0}}{2}\right)^{2}+\left(p-\frac{p_{0}}{2}\right)^{2}\right] .
$$




## Examples

## Jaynes-Cummings Hamiltonian

Classical Hamiltonian postulated as

$$
H= \pm g \sqrt{\frac{p^{2}+x^{2}}{2}}
$$

Stems from the quantum Hamiltonian

$$
\hat{H}_{J C}=g\left(\hat{a} \hat{\sigma}_{+}+\hat{a}^{\dagger} \hat{\sigma}_{-}\right),
$$

assume the initial quantum state prepared as

$$
\left|\Phi_{ \pm}\right\rangle=|\alpha\rangle \otimes \frac{1}{\sqrt{2}}\left(|g\rangle \pm e^{i \varphi}|e\rangle\right)
$$

with $\alpha=\sqrt{n} e^{i \varphi}=2^{-1 / 2}(x+i p)$.
The mean energy is $\left\langle\Phi_{ \pm}\right| \hat{H}_{J C}\left|\Phi_{ \pm}\right\rangle= \pm g \sqrt{n}= \pm 2^{-1 / 2} g \sqrt{x^{2}+p^{2}}$.

## Examples

## Jaynes-Cummings Hamiltonian

$H= \pm g \sqrt{\frac{p^{2}+x^{2}}{2}}$, visualization:


## Examples

## Jaynes-Cummings Hamiltonian

Squeezing rate

$$
Q=\frac{g}{\sqrt{2}} \frac{1}{\sqrt{x^{2}+p^{2}}}
$$

angular velocities

$$
\begin{aligned}
\omega_{v} & = \pm \frac{g}{\sqrt{2}} \frac{1}{2 \sqrt{x^{2}+p^{2}}} \\
\omega_{c} & = \pm \frac{g}{\sqrt{2}} \frac{1}{\sqrt{x^{2}+p^{2}}} \\
\left(x_{r}, p_{r}\right) & =\left(-x_{0},-p_{0}\right)
\end{aligned}
$$

Compensating Hamiltonian:

$$
H_{\mathrm{ad}}=\mp \frac{g}{4 \sqrt{2} \sqrt{x_{0}^{2}+p_{0}^{2}}}\left[\left(x+x_{0}\right)^{2}+\left(p+p_{0}\right)^{2}\right] .
$$

## Examples

## Jaynes-Cummings Hamiltonian

Phase trajectories


Squeezing with classical Hamiltonians

- Squeezing rate for planar phase-space $Q=\sqrt{\left(H_{p p}-H_{x x}\right)^{2}+4 H_{x p}^{2}}$,

$$
\dot{V}_{ \pm}= \pm Q V_{ \pm}
$$

- Interpretation: for zero-gradient points, difference of principal curvatures of the Hamiltonian
- Add non-squeezing Hamiltonians to keep the state at right place and optimally oriented

For initial stages of squeezing, classical formulas perfectly agree with quantum predictions.

