

Palacký University Olomouc

Squeezing of quantum states

Tomáš Opatrný

Faculty of Science, Palacky University Olomouc

Squeezing of quantum states

- Introduction
- Motivation: why squeezing?
- Basics of squeezing
- Hamilton canonical equations and squeezing rate

Havranipol

- Examples
- Conclusion



Metrology: suppressed noise of interferometers

- optics:detection of gravitational waves
- squeezed atomic spin states: magnetometry
- atomic clocks
- Quantum information processing: irreducble resource
 - quantum teleportation of continuous variables
 - quantum cryptography
 - quantum computation with continuous variables



Measurement noise 100 times lower than the quantum-projection limit using entangled atoms



[Hosten et al. (Kasevich group)]

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Gravitational wave detection, LIGO



[www.ligo.caltech.edu; PRL 116, 061102 (2016)]

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Gravitational wave detection: GEO600 (LIGO collaboration), R. Schnabel



[Abadie et al., Nature Physics, 7, 962-965 (2011)]

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Quantum information processing with squeezed states

- Quantum teleportation of continuous variables [Vaidman, PRA 49, 1473 (1994)].
- Quantum cryptography with continuous variables (e.g., [Hillery, PRA 61, 022309 (2000)]
- Quantum computation with continuous variables (e.g., [Lloyd & Braunstein, PRL 82, 1784 (1999)])
 - Analogue computation,
 - quantum simulators,
 - to have universal computer, necessary to have Hamiltonian of higher than quadratic nonlinearity in x and p.



Squeezing Example: harmonic oscillator

Hamiltonian:

$$H = \frac{\hat{p}^2}{2m} + \frac{1}{2}m\omega^2\hat{x}^2$$

Coherent states: saturate uncertainty relation

$$\Delta x = \sqrt{\frac{\hbar}{2m\omega}}$$
$$\Delta p = \sqrt{\frac{\hbar m\omega}{2}}$$
$$\Delta x \Delta p = \frac{\hbar}{2}$$



Squeezing

Example: harmonic oscillator Coherent states: saturate uncertainty relation



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Squeezing

Example: harmonic oscillator Creation and annihilation operators:

$$\hat{x} = \sqrt{\frac{\hbar}{2m\omega}} (\hat{a} + \hat{a}^{\dagger})$$

$$\hat{p} = -i\sqrt{\frac{\hbar m\omega}{2}} (\hat{a} - \hat{a}^{\dagger})$$

$$\begin{bmatrix} \hat{x}, \hat{p} \end{bmatrix} = i\hbar$$

$$\begin{bmatrix} \hat{a}, \hat{a}^{\dagger} \end{bmatrix} = 1$$

$$H = \hbar \left(\hat{a}^{\dagger} \hat{a} + \frac{1}{2} \right)$$

V

Squeezing

Example: harmonic oscillator Squeezed coherent states: can also saturate uncertainty relation, but, e.g.:



Basics of squeezing: detection



Basics of squeezing: detection



Basics of squeezing: detection



Noise squeezing [G. Breitenbach dissertation, 1998; Nature 387, 471 (1997)]





Parametric down-conversion

$${\it H}=\chi(\hat{b}\,\,\hat{a}_1^\dagger\hat{a}_2^\dagger+\hat{b}^\dagger\hat{a}_1\hat{a}_2)$$

Parametric down-conversion, degenerate case

$$H=\chi(\hat{b}\,\,\hat{a}^{\dagger2}+\hat{b}^{\dagger}\hat{a}^2)$$



Kerr nonlinearity

(index of refraction proportional to light intensity)

 $H = \chi \hat{n}^2$

Strong pulses propagating in optical fibres





[C. W. Woods and J. Gea-Banacloche, J. Mod. Opt. 40, 2361-2379 (1993)]

Classical Hamiltonian H(x, p), equations of motion

$$\dot{x} = \frac{\partial H}{\partial p},$$

 $\dot{p} = -\frac{\partial H}{\partial x}.$

Continuity equation

$$\frac{\partial \varrho}{\partial t} = -\sum_{k} \frac{\partial j_{k}}{\partial q_{k}}$$
$$j_{k} = \varrho \dot{q}_{k}.$$

Liouville theorem

$$\frac{d\varrho}{dt} = 0$$

Phase space is the countryside, Hamiltonian is the elevation



Rules of motion:

- Follow the countour line (constant elevation), hill on your left, valley on your right,
- speed is proportional to the slope magnitude.



Phase space is the countryside, Hamiltonian is the elevation



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Derivation of the squeezing rate Variation matrix

$$V = \left(egin{array}{cc} \langle \Delta x^2
angle & \langle \Delta x \Delta p
angle \\ \langle \Delta x \Delta p
angle & \langle \Delta p^2
angle \end{array}
ight) \equiv \left(egin{array}{cc} V_{xx} & V_{xp} \\ V_{xp} & V_{pp} \end{array}
ight),$$

for a state centered in (x_0, p_0) .



Derivation of the squeezing rate

Change of position

$$\begin{split} \tilde{x}_{0} + \Delta \tilde{x} &\approx x_{0} + \Delta x + \frac{d}{dt} (x_{0} + \Delta x) dt \\ &= x_{0} + \Delta x + \frac{\partial H(x_{0} + \Delta x, p_{0} + \Delta p)}{\partial p} dt \\ &\approx x_{0} + \Delta x + \frac{\partial H(x_{0}, p_{0})}{\partial p} dt \\ &+ \left(\frac{\partial^{2} H(x_{0}, p_{0})}{\partial p^{2}} \Delta p + \frac{\partial^{2} H(x_{0}, p_{0})}{\partial x \partial p} \Delta x \right) dt \end{split}$$



Derivation of the squeezing rate

Change of momentum

$$egin{aligned} ilde{p} &\approx p_0 + \Delta p + rac{d}{dt} \left(p_0 + \Delta p
ight) dt \ &= p_0 + \Delta p - rac{\partial H(x_0 + \Delta x, p_0 + \Delta p)}{\partial x} dt \ &pprox p_0 + \Delta p - rac{\partial H(x_0, p_0)}{\partial x} dt \ &- \left(rac{\partial^2 H(x_0, p_0)}{\partial x^2} \Delta x + rac{\partial^2 H(x_0, p_0)}{\partial x \partial p} \Delta p
ight) dt. \end{aligned}$$



Derivation of the squeezing rate New central position and momentum:

$$\begin{split} & \tilde{x}_0 & pprox x_0 + H_p dt, \ & \tilde{p}_0 & pprox p_0 - H_x dt, \end{split}$$

new deviations:

$$\Delta \tilde{x} \approx \Delta x + (H_{xp}\Delta x + H_{pp}\Delta p) dt,$$

$$\Delta \tilde{p} \approx \Delta p - (H_{xp}\Delta p + H_{xx}\Delta x) dt.$$



Derivation of the squeezing rate

Assuming $\langle \Delta x \rangle = \langle \Delta p \rangle = 0$, the new variances are (up to the first order in dt)

$$\Delta \tilde{x}^2 \rangle \approx \langle \Delta x^2 \rangle + 2 \left(H_{xp} \langle \Delta x^2 \rangle + H_{pp} \langle \Delta x \Delta p \rangle \right) dt,$$

 $\langle \Delta \tilde{p}^2 \rangle ~\approx~ \langle \Delta p^2 \rangle - 2 \left(H_{xp} \langle \Delta p^2 \rangle + H_{xx} \langle \Delta x \Delta p \rangle \right) dt,$

 $\langle \Delta \tilde{x} \Delta \tilde{p} \rangle ~\approx~ \langle \Delta x \Delta p \rangle + \left(\mathcal{H}_{pp} \langle \Delta p^2 \rangle - \mathcal{H}_{xx} \langle \Delta x^2 \rangle \right) dt.$



Derivation of the squeezing rate

In terms of the variation matrix:

$$\tilde{V} = SVS^T$$
,

where

$$S = \begin{pmatrix} 1 + H_{xp}dt & H_{pp}dt \\ -H_{xx}dt & 1 - H_{xp}dt \end{pmatrix}$$

V

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Derivation of the squeezing rate

For initially isotropic and uncorrelated fluctuations, i.e., $\langle \Delta x^2 \rangle = \langle \Delta p^2 \rangle = \sigma^2$, and $\langle \Delta x \Delta p \rangle = 0$:

$$egin{array}{lll} \langle \Delta ilde{x}^2
angle &pprox \ \sigma^2 \left(1+2H_{xp}
ight) dt, \ \langle \Delta ilde{p}^2
angle &pprox \ \sigma^2 \left(1-2H_{xp}
ight) dt, \ \langle \Delta ilde{x} \Delta ilde{p}
angle &pprox \ \sigma^2 \left(H_{pp}-H_{xx}
ight) dt. \end{array}$$

Eigenvalues of the new variance matrix \tilde{V} :

$$ilde{V}_{\pm} \;\; = \;\; rac{\langle \Delta ilde{x}^2
angle + \langle \Delta ilde{p}^2
angle}{2} \pm rac{1}{2} \sqrt{\left(\langle \Delta ilde{x}^2
angle - \langle \Delta ilde{p}^2
angle
ight)^2 + 4 \langle \Delta ilde{x} \Delta ilde{p}
angle^2}.$$



Derivation of the squeezing rate

Inserting the transformed variance:

$$ilde{V}_{\pm}=~\sigma^2\left(1\pm {\cal Q} dt
ight)$$

where

$$Q = \sqrt{(H_{pp} - H_{xx})^2 + 4H_{xp}^2}$$

is the **squeezing rate**. [T.O., PRA **92,** 033801 (2015)]



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Orientation and rotation of the squeezing ellipse

Transformation matrix S, general starting variance matrix:

$$S = \begin{pmatrix} \cos(\phi - \epsilon) & -\sin(\phi - \epsilon) \\ \sin(\phi - \epsilon) & \cos(\phi - \epsilon) \end{pmatrix} \begin{pmatrix} 1 + \frac{Qdt}{2} & 0 \\ 0 & 1 - \frac{Qdt}{2} \end{pmatrix} \times \begin{pmatrix} \cos\phi & \sin\phi \\ \sin\phi & \cos\phi \end{pmatrix}.$$

$$(a) \qquad \Delta p \qquad (b) \qquad \Delta p$$

$$V \qquad 0 \qquad 0 \qquad \Delta p$$

$$V \qquad 0 \qquad 0 \qquad \Delta x$$
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Orientation and rotation of the squeezing ellipse

Up to the first order in ϵ and dt, one finds

$$S = \begin{pmatrix} 1 + \frac{Qdt}{2}\cos 2\phi & \epsilon + \frac{Qdt}{2}\sin 2\phi \\ -\epsilon + \frac{Qdt}{2}\sin 2\phi & 1 - \frac{Qdt}{2}\cos 2\phi \end{pmatrix}$$

Comparing this with Eq. (1) one finds

$$Q \cos 2\phi = 2H_{xp},$$

$$Q \sin 2\phi = H_{pp} - H_{xx},$$

$$2\epsilon = (H_{xx} + H_{pp}) dt$$

with Q given by Eq. (2).



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Orientation and rotation of the squeezing ellipse

Rotation angle

$$\tan 2\phi = \frac{H_{pp} - H_{xx}}{2H_{xp}}$$

and assuming that ϵ evolves with time as $\epsilon = \omega_v dt$, one gets

$$\omega_{v} = \frac{H_{xx} + H_{pp}}{2} \tag{4}$$



Compensation of motion of the uncertainty ellipse

Rotation center at $(x_R, p_R) = (x, p) + (R_x, R_p)$ with

$$R_x = -\frac{H_x}{\omega_c}, \qquad R_p = -\frac{H_p}{\omega_c},$$

angular frequency of the motion of the center

$$\omega_c = \frac{H_x^2 H_{pp} + H_p^2 H_{xx} - 2H_x H_p H_{xp}}{H_x^2 + H_p^2}$$



 (x_R, p_R)

(5)

Compensation of motion of the uncertainty ellipse

To compensate the drift, add the Hamiltonian

$$H_{\rm ad1} = -\frac{1}{2}\omega_c \left[(x - x_R)^2 + (p - p_R)^2 \right]$$

To keep the optimal orientation, add

$$H_{
m ad2} = -rac{1}{2}(\omega_v - \omega_c)\left[(x - x_0)^2 + (p - p_0)^2
ight]$$

Combined Hamiltonian $H_{ad} = H_{ad1} + H_{ad2}$,

$$H_{\rm ad} = -\frac{1}{2}\omega_{\rm v}\left[(x-x_r)^2 + (p-p_r)^2\right] + const.,$$

with the center localized at

$$(x_r, p_r) = (x_R, p_R) + \left(1 - \frac{\omega_c}{\omega_v}\right)(x_0 - x_R, p_0 - p_R).$$

(6)

Harmonic oscillator

$$H=\frac{1}{2}\omega(p^2+x^2)$$

Eq. (2) yields Q = 0. Rotation frequencies $\omega_v = \omega_c = \omega$.



Free particle

$$H=\frac{1}{2m}p^2.$$

Squeezing rate Q = 1/m, optimum orientation of the uncertainty ellipse $\theta = \pi/4$, rotations $\omega_v = 1/(2m)$, and $\omega_c = 0$.



Free particle

In terms of quantum optical bosonic operators:

$$egin{array}{rcl} \hat{x} &=& rac{1}{\sqrt{2}}\left(\hat{a}^{\dagger}+\hat{a}
ight), \ \hat{p} &=& rac{i}{\sqrt{2}}\left(\hat{a}^{\dagger}-\hat{a}
ight), \end{array}$$

the Hamiltonian is

$$\mathcal{H}=rac{1}{2}\hat{p}^2=-rac{1}{4}\left(\hat{a}^{\dagger2}+\hat{a}^2
ight)+rac{1}{2}\left(\hat{a}^{\dagger}\hat{a}+rac{1}{2}
ight),$$

i.e., parametric down-conversion plus harmonic oscillator.

Inverted oscillator

$$\frac{1}{2}\zeta(p^2-x^2)$$

Squeezing rate $Q = 2\zeta$, optimum orientation $\theta = \pi/4$, no rotation, $\omega_v = 0$.



xp-Hamiltonian

$H = \zeta x p$

Classical counterpart of the quantum operator

$$\hat{H}=rac{1}{2}\zeta\left(\hat{x}\hat{p}+\hat{p}\hat{x}
ight)=rac{i}{2}\zeta\left(\hat{a}^{\dagger2}-\hat{a}^{2}
ight),$$

i.e., parametric down-conversion. Squeezing rate $Q = 2\zeta$, optimum orientation $\theta = 0$, no rotation, $\omega_v = 0$.



Pendulum

$$H = \frac{1}{2}p^2 - \cos x$$

Squeezing rate

$$Q = 1 - \cos x = 2\sin^2 \frac{x}{2},$$

rotation $\omega_{v} = \cos^{2} \frac{x}{2}$

Kerr nonlinearity

$$H = \chi (p^2 + x^2)^2$$

Squeezing rate

$$Q=8\chi(p^2+x^2),$$

rotation

$$\begin{array}{rcl} \omega_{v} &=& 8\chi(p^{2}+x^{2}),\\ \omega_{c} &=& 4\chi(p^{2}+x^{2}),\\ (x_{r},p_{r}) &=& \frac{1}{2}(x_{0},p_{0}). \end{array}$$

Kerr nonlinearity

Compensating Hamiltonian

$$H_{\rm ad} = -4\chi(x_0^2 + p_0^2)\left[\left(x - \frac{x_0}{2}\right)^2 + \left(p - \frac{p_0}{2}\right)^2\right].$$



Jaynes-Cummings Hamiltonian

Classical Hamiltonian postulated as

$$H = \pm g \sqrt{rac{p^2 + x^2}{2}}$$

Stems from the quantum Hamiltonian

$$\hat{H}_{JC}=g\left(\hat{a}\hat{\sigma}_{+}+\hat{a}^{\dagger}\hat{\sigma}_{-}
ight)$$

assume the initial quantum state prepared as

$$|\Phi_{\pm}
angle = |lpha
angle \otimes rac{1}{\sqrt{2}}\left(|g
angle \pm e^{iarphi}|e
angle
ight),$$

with $\alpha = \sqrt{n}e^{i\varphi} = 2^{-1/2}(x + ip)$. The mean energy is $\langle \Phi_{\pm}|\hat{H}_{JC}|\Phi_{\pm}\rangle = \pm g\sqrt{n} = \pm 2^{-1/2}g\sqrt{x^2 + p^2}$.



Jaynes-Cummings Hamiltonian Squeezing rate

$$Q=\frac{g}{\sqrt{2}}\frac{1}{\sqrt{x^2+p^2}},$$

angular velocities

$$\begin{split} \omega_{v} &= \pm \frac{g}{\sqrt{2}} \frac{1}{2\sqrt{x^{2} + p^{2}}}, \\ \omega_{c} &= \pm \frac{g}{\sqrt{2}} \frac{1}{\sqrt{x^{2} + p^{2}}}, \\ (x_{r}, p_{r}) &= (-x_{0}, -p_{0}). \end{split}$$

Compensating Hamiltonian:

$$H_{\rm ad} = \mp \frac{g}{4\sqrt{2}\sqrt{x_0^2 + p_0^2}} \left[(x + x_0)^2 + (p + p_0)^2 \right].$$

Jaynes-Cummings Hamiltonian Phase trajectories (b) (a) 5 5 р p 0 0 -5 -5 $\frac{1}{x}$ 0 x⁵ 10 10 0

Summary

Squeezing with classical Hamiltonians

- Squeezing rate for planar phase-space $Q = \sqrt{(H_{pp} H_{xx})^2 + 4H_{xp}^2}$, $\dot{V}_{\pm} = \pm QV_{\pm}$.
- Interpretation: for zero-gradient points, difference of principal curvatures of the Hamiltonian
- Add non-squeezing Hamiltonians to keep the state at right place and optimally oriented

For initial stages of squeezing, classical formulas perfectly agree with quantum predictions.